

1. General description

The HEF4021B is an 8-bit static shift register (parallel-to-serial converter) with a synchronous serial data input (DS), a clock input (CP), an asynchronous active HIGH parallel load input (PL), eight asynchronous parallel data inputs (D0 to D7) and buffered parallel outputs from the last three stages (Q5 to Q7).

Each register stage is a D-type master-slave flip-flop with a set direct (SD) and clear direct (CD) input. Information on D0 to D7 is asynchronously loaded into the register while PL is HIGH, independent of CP and DS. When PL is LOW, data on DS is shifted into the first register position and all the data in the register is shifted one position to the right on the LOW-to-HIGH transition of CP. Schmitt trigger action makes the clock input highly tolerant of slower rise and fall times.

It operates over a recommended V_{DD} power supply range of 3 V to 15 V referenced to V_{SS} (usually ground). Unused inputs must be connected to V_{DD} , V_{SS} , or another input.

2. Features and benefits

- Tolerant of slower rise and fall times
- Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- Specified from –40 °C to +125 °C
- Complies with JEDEC standard JESD 13-B

3. Ordering information

Table 1.Ordering information

All types operate from -40 °C to +125 °C.

Type number	Package	Package						
	Name	Description	Version					
HEF4021BT	SO16	plastic small outline package; 16 leads; body width 3.9 mm	SOT109-1					
HEF4021BTT	TSSOP16	plastic thin shrink small outline package; 16 leads; body width 4.4 mm	SOT403-1					

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8-bit static shift register

4. Functional diagram



5. Pinning information

5.1 Pinning



5.2 Pin description

Table 2. Pin description

Symbol	Pin	Description	
Q5 to Q7	2, 12, 3	buffered parallel output from the last three stages	
D0 to D7	7, 6, 5, 4, 13, 14,15, 1	parallel data input	
V _{SS}	8	ground supply voltage	
PL	9	parallel load input	
СР	10	clock input (LOW-to-HIGH edge-triggered)	
DS	11	serial data input	
V _{DD}	16	supply voltage	

6. Functional description

Table 3.Function table^[1]

Number of clock	Inputs			Outputs		
transitions	СР	DS	PL	Q5	Q6	Q7
Serial operation		I				
1	↑	data 1	L	Х	Х	Х
2	↑	data 2	L	Х	Х	Х
3	\uparrow	data 3	L	Х	х	Х
6	\uparrow	X	L	data 1	х	Х
7	\uparrow	X	L	data 2	data 1	Х
8	\uparrow	X	L	data 3	data 2	data 1
	\downarrow	X	L	no change	no change	no change
Parallel operation	1	1		1		1
	Х	Х	Н	D5	D6	D7

[1] H = HIGH voltage level; L = LOW voltage level; X = don't care; \uparrow = LOW to HIGH clock transition; \downarrow = HIGH to LOW clock transition; data n = data (HIGH or LOW) on the DS input at the nth \uparrow CP transition.

7. Limiting values

Table 4. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit
V _{DD}	supply voltage		-0.5	+18	V
I _{IK}	input clamping current	$V_{I} < -0.5$ V or $V_{I} > V_{DD} + 0.5$ V	-	±10	mA
VI	input voltage		-0.5	V _{DD} + 0.5	V
I _{OK}	output clamping current	V_{O} < -0.5 V or V_{O} > V_{DD} + 0.5 V	-	±10	mA
I _{I/O}	input/output current		-	±10	mA
I _{DD}	supply current		-	50	mA
T _{stg}	storage temperature		-65	+150	°C
T _{amb}	ambient temperature		-40	+125	°C
P _{tot}	total power dissipation	T _{amb} –40 °C to +125 °C			
		SO16 and TSSOP16 package [1]	-	500	mW
Р	power dissipation	per output	-	100	mW

For SO16 package: P_{tot} derates linearly with 8 mW/K above 70 °C.
 For TSSOP16 package: P_{tot} derates linearly with 5.5 mW/K above 60 °C.

8. Recommended operating conditions

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
V _{DD}	supply voltage		3	-	15	V
VI	input voltage		0	-	V _{DD}	V
T _{amb}	ambient temperature	in free air	-40	-	+125	°C
Δt/ΔV	input transition rise and fall rate	$V_{DD} = 5 V$	-	-	3.75	μs/V
		V _{DD} = 10 V	-	-	0.5	μs/V
		V _{DD} = 15 V	-	-	0.08	μs/V

Table 5. Recommended operating conditions

9. Static characteristics

Table 6. Static characteristics

 $V_{SS} = 0$ V; $V_I = V_{SS}$ or V_{DD} unless otherwise specified.

Symbol	Parameter	Conditions	V _{DD}	T _{amb} =	–40 °C	T _{amb} =	25 °C	T _{amb} =	85 °C	T _{amb} =	125 °C	Unit
				Min	Max	Min	Max	Min	Max	Min	Max	
VIH	V _{IH} HIGH-level	I _O < 1 μA	5 V	3.5	-	3.5	-	3.5	-	3.5	-	V
	input voltage	voltage	10 V	7.0	-	7.0	-	7.0	-	7.0	-	V
			15 V	11.0	-	11.0	-	11.0	-	11.0	-	V
V _{IL}	LOW-level	I _O < 1 μA	5 V	-	1.5	-	1.5	-	1.5	-	1.5	V
	input voltage		10 V	-	3.0	-	3.0	-	3.0	-	3.0	V
			15 V	-	4.0	-	4.0	-	4.0	-	4.0	V
V _{OH}	HIGH-level	I _O < 1 μA	5 V	4.95	-	4.95	-	4.95	-	4.95	-	V
	output voltage		10 V	9.95	-	9.95	-	9.95	-	9.95	-	V
	vollage		15 V	14.95	-	14.95	-	14.95	-	14.95	-	V
V _{OL}	LOW-level	I _O < 1 μA	5 V	-	0.05	-	0.05	-	0.05	-	0.05	V
	output voltage		10 V	-	0.05	-	0.05	-	0.05	-	0.05	V
	vollage		15 V	-	0.05	-	0.05	-	0.05	-	0.05	V
I _{OH}	HIGH-level	V _O = 2.5 V	5 V	-	-1.7	-	-1.4	-	-1.1	-	-1.1	mA
	output current	V _O = 4.6 V	5 V	-	-0.64	-	-0.5	-	-0.36	-	-0.36	mA
		V _O = 9.5 V	10 V	-	-1.6	-	-1.3	-	-0.9	-	-0.9	mA
		V _O = 13.5 V	15 V	-	-4.2	-	-3.4	-	-2.4	-	-2.4	mA
I _{OL}	LOW-level	$V_{O} = 0.4 V$	5 V	0.64	-	0.5	-	0.36	-	0.36	-	mA
	output current	V _O = 0.5 V	10 V	1.6	-	1.3	-	0.9	-	0.9	-	mA
		V _O = 1.5 V	15 V	4.2	-	3.4	-	2.4	-	2.4	-	mA
I _I	input leakage current	V _{DD} = 15 V	15 V	-	±0.1	-	±0.1	-	±1.0	-	±1.0	μΑ
I _{DD}	supply	I _O = 0 A	5 V	-	5	-	5	-	150	-	150	μA
	current		10 V	-	10	-	10	-	300	-	300	μA
			15 V	-	20	-	20	-	600	-	600	μA
Cı	input capacitance		-	-	-	-	7.5	-	-	-	-	pF

10. Dynamic characteristics

Table 7. Dynamic characteristics

 $V_{SS} = 0$ V; $T_{amb} = 25$ °C; for test circuit see <u>Figure 7</u>; unless otherwise specified.

Symbol	Parameter	Conditions	V _{DD}	Extrapolation formula	Min	Тур	Max	Unit
t _{PHL}	HIGH to LOW	CP to Qn	5 V [□ 98 ns + (0.55 ns/pF)C _L	-	125	250	ns
	propagation delay	see Figure 4	10 V	44 ns + (0.23 ns/pF)C _L	-	55	110	ns
			15 V	32 ns + (0.16 ns/pF)C _L	-	40	80	ns
		$ \begin{array}{ c c c c c } PL \mbox{ to Qn} & 5 \end{tabular} & 93 \mbox{ ns + (0.55 \ ns/pF)C_L} \\ \hline PL \mbox{ to Qn} & 5 \end{tabular} & 44 \ ns + (0.23 \ ns/pF)C_L \\ \hline 10 \end{tabular} & 44 \ ns + (0.23 \ ns/pF)C_L \\ \hline 15 \end{tabular} & 32 \ ns + (0.16 \ ns/pF)C_L \\ \hline 15 \end{tabular} & 5 \end{tabular} & 10 \end{tabular} & 39 \ ns + (0.23 \ ns/pF)C_L \\ \hline 15 \end{tabular} & 32 \ ns + (0.16 \ ns/pF)C_L \\ \hline PL \mbox{ to Qn} & 5 \end{tabular} & 78 \ ns + (0.23 \ ns/pF)C_L \\ \hline 15 \end{tabular} & 39 \ ns + (0.23 \ ns/pF)C_L \\ \hline 15 \end{tabular} & 39 \ ns + (0.23 \ ns/pF)C_L \\ \hline 15 \end{tabular} & 39 \ ns + (0.23 \ ns/pF)C_L \\ \hline 15 \end{tabular} & 39 \ ns + (0.23 \ ns/pF)C_L \\ \hline 15 \end{tabular} & 32 \ ns + (0.16 \ ns/pF)C_L \\ \hline 15 \end{tabular} & 32 \ ns + (0.16 \ ns/pF)C_L \\ \hline 15 \end{tabular} & 32 \ ns + (0.16 \ ns/pF)C_L \\ \hline 15 \end{tabular} & 32 \ ns + (0.42 \ ns/pF)C_L \\ \hline 10 \end{tabular} & 9 \ ns + (0.42 \ ns/pF)C_L \\ \hline 10 \end{tabular} & 9 \ ns + (0.42 \ ns/pF)C_L \\ \hline 15 \end{tabular} & 9 \ ns + (0.28 \ ns/pF)C_L \\ \hline 15 \end{tabular} & 9 \ ns + (0.28 \ ns/pF)C_L \\ \hline 15 \end{tabular} & 9 \ ns + (0.28 \ ns/pF)C_L \\ \hline 15 \end{tabular} & 9 \ ns + (0.28 \ ns/pF)C_L \\ \hline 15 \end{tabular} & 9 \ ns + (0.28 \ ns/pF)C_L \\ \hline 15 \end{tabular} & 10 \end{tabular} & 9 \ ns + (0.28 \ ns/pF)C_L \\ \hline 15 \end{tabular} & 10 \end{tabular} & 9 \ ns + (0.28 \ ns/pF)C_L \\ \hline 15 \end{tabular} & 10 \end{tabular} & 9 \ ns + (0.28 \ ns/pF)C_L \\ \hline 15 \end{tabular} & 10 \end{tabular} & 1$	-	120	240	ns		
		see Figure 4	10 V	44 ns + (0.23 ns/pF)C _L	-	55	110	ns
			15 V	32 ns + (0.16 ns/pF)C _L	-	40	80	ns
t _{PLH}	LOW to HIGH		5 V 🕻	1 88 ns + (0.55 ns/pF)C _L	-	115	230	ns
	propagation delay	see Figure 4	10 V	39 ns + (0.23 ns/pF)C _L	-	50	100	ns
			15 V	32 ns + (0.16 ns/pF)C _L	-	40	80	ns
			5 V	78 ns + (0.55 ns/pF)C _L	-	105	210	ns
		see Figure 4	10 V	39 ns + (0.23 ns/pF)C _L	-	50	100	ns
			15 V	32 ns + (0.16 ns/pF)CΛ	-	40	80	ns
t _t	transition time	Qn; see Figure 4	5 V [10 ns + (1.00 ns/pF)C _L	-	60	120	ns
			10 V	9 ns + (0.42 ns/pF)C _L	-	30	60	ns
			15 V	6 ns + (0.28 ns/pF)C _L	-	20	40	ns
t _{su} set-up time		5 V		+25	-15	-	ns	
		see Figure 5	10 V		+25	-10	-	ns
			15 V		+15	-5	-	ns
			5 V		50	25	-	ns
		see Figure 6	10 V		30	10	-	ns
			15 V		20	5	-	ns
t _h	hold time		5 V		40	20	-	ns
		see Figure 5	10 V		20	10	-	ns
			15 V		15	8	-	ns
		-	5 V		+15	-10	-	ns
		see Figure 6	10 V		15	0	-	ns
			15 V		15	0	-	ns
t _W	pulse width	CP = LOW;	5 V		70	35	-	ns
		minimum width;	10 V		30	15	-	ns
		see Figure 5	15 V		24	12	-	ns
		PL = HIGH;	5 V		70	35	-	ns
		minimum width;	10 V		30	15	-	ns
		see Figure 6	15 V		24	12	-	ns
t _{rec}	recovery time	PL input;	5 V		50	10	-	ns
		see Figure 6	10 V		40	5	-	ns
			15 V		35	5	-	ns

Table 7. Dynamic characteristics ...continued

 $V_{SS} = 0$ V; $T_{amb} = 25$ °C; for test circuit see Figure 7; unless otherwise specified.

Symbol	Parameter	Conditions	V _{DD}	Extrapolation formula	Min	Тур	Max	Unit
f _{clk(max)}	maximum clock	CP input;	5 V		6	13	-	MHz
	frequency	see Figure 5	10 V		15	30	-	MHz
			15 V		20	40	-	MHz

[1] The typical values of the propagation delay and transition times are calculated from the extrapolation formulas shown (C_L in pF).

Table 8. Dynamic power dissipation P_D

 P_D can be calculated from the formulas shown. $V_{SS} = 0$ V; $t_r = t_f \le 20$ ns; $T_{amb} = 25$ °C.

Symbol	Parameter	V _{DD}	Typical formula for P_D (μ W)	where:
PD	dynamic power	5 V	$P_D = 900 \times f_i + \Sigma(f_o \times C_L) \times V_DD^2$	$f_i = input frequency in MHz,$
	dissipation	10 V	$P_D = 4300 \times f_i + \Sigma(f_o \times C_L) \times V_DD^2$	$f_o = output frequency in MHz,$
		15 V	$P_{D} = 12000 \times f_{i} + \Sigma (f_{o} \times C_{L}) \times V_{DD}^{2}$	C_L = output load capacitance in pF,
				V_{DD} = supply voltage in V,
				$\Sigma(f_o \times C_L)$ = sum of the outputs.

11. Waveforms



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Table 9. Measurement points

Supply voltage	Input	Output			
V _{DD}	V _M	V _M	V _X	V _Y	
5 V to 15 V	0.5V _{DD}	0.5V _{DD}	0.1V _{DD}	0.9V _{DD}	

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Supply voltage	Input		Load
V _{DD}	VI	t _r , t _f	CL
5 V to 15 V	V_{SS} or V_{DD}	≤ 20 ns	50 pF

12. Package outline



Fig 8. Package outline SOT109-1 (SO16)

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TSSOP16: plastic thin shrink small outline package; 16 leads; body width 4.4 mm

Package outline SOT403-1 (TSSOP16) Fig 9.

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13. Revision history

Table 11. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
HEF4021B v.10	20160321	Product data sheet	-	HEF4021B v.9
Modifications:	Type number	HEF4021BP (SOT38-4) remo	ved.	
HEF4021B v.9	20130830	Product data sheet	-	HEF4021B v.8
Modifications:	 added type n 	umber HEF4021BTT.		
HEF4021B v.8	20111118	Product data sheet	-	HEF4021B v.7
Modifications:	Legal pages	updated.		
	Changes in "	General description" and "Feat	ures and benefits".	
	 Section "Appl 	ications" removed.		
HEF4021B v.7	20111010	Product data sheet	-	HEF4021B v.6
HEF4021B v.6	20091127	Product data sheet	-	HEF4021B v.5
HEF4021B v.5	20090707	Product data sheet	-	HEF4021B v.4
HEF4021B v.4	20081110	Product data sheet	-	HEF4021B_CNV v.3
HEF4021B_CNV v.3	19950101	Product specification	-	HEF4021B_CNV v.2
HEF4021B_CNV v.2	19950101	Product specification	-	-

14. Legal information

14.1 Data sheet status

Document status[1][2]	Product status ^[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

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HEF4021B

16. Contents

1	General description 1
2	Features and benefits 1
3	Ordering information 1
4	Functional diagram 2
5	Pinning information 3
5.1 5.2	Pinning
6	Functional description 4
7	Limiting values
8	Recommended operating conditions 5
9	Static characteristics 5
10	Dynamic characteristics 6
11	Waveforms
12	Package outline 10
13	Revision history 12
14	Legal information 13
14.1	Data sheet status 13
14.2	Definitions
14.3	Disclaimers
14.4	Trademarks 14
15	Contact information 14
16	Contents 15